

Docket No. 3351-048

IMAGE ENHANCEMENT

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Related Application

The present application is related to co-pending patent application entitled "VIDEO MOSAIC", (Docket No. 3351-042) and assigned to the instant assignee and filed on even date herewith and is hereby incorporated by reference in its 10 entirety into this specification in its entirety.

Field of the Invention

The present invention is related generally to video mosaics, and more particularly, to an image enhancement process used in conjunction with a video mosaic process.

15 Background of the Invention

Until recently, image processing systems have generally processed images, such as frames of video, still photographs, and the like in an individual manner. After processing, the individual images are combined to form a mosaic, i.e., an image that contains a plurality of individual images. Additional image 20 processing is performed on the mosaic to ensure that the seams between the images are invisible such that the mosaic looks like a single large image. The alignment was previously done manually by a technician to remove the seams. In

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such computer aided processing systems, the technician manually selects processed images, manually aligns those images, and a computer applies various images combining processes to the images to remove any seams or gaps between the images.

5 One problem that has been noted with respect to video mosaics is that the video mosaics produce low resolution images because the video images are low resolution images. One proposed solution is disclosed in a final Technical Report No. RL-TR-96-21, entitled "Multiframe Integration for High-Resolution Video Stills", by Dr. Robert L. Stevenson and Dr. Richard R. Schultz. Although the
10 solution proposed in this report provides excellent results, the drawback to the solution is there requires significant processing complexity. A need still exists in the art for an image enhancement process which can be performed by computer processing equipment mounted on an unmanned *air*iel vehicle (UAV).

15 Summary of the Invention

It is, therefore, an object of the present invention to provide an image enhancement process and system which requires minimal computer processing capability.

It is another object of the present invention to provide an image
20 enhancement process and system which can be performed on-board a vehicle such as a UAV taking a sequence of video images.

Another object of the present invention is to provide an image enhancement process in which the sequence of video images is upsampled. Registration is then performed to align the images and then one enhanced video
25 image is formed.

These and other objects of the present invention are achieved by a computer-implemented method of enhancing a video image. A sequence of video frames is extracted. Each of the video frames is upsampled. The upsampled

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video frames are interpolated. The interpolated video frames are aligned and a single image is created from the aligned video frames.

The foregoing and other objects of the present invention are achieved by a computer architecture. A sequence of video frames is extracted. each of the
5 video frames is upsampled. The upsampled video frames are interpolated. The interpolated video frames are aligned and a single image is created from the aligned frames.

The foregoing and other objects of the present invention are achieved by an article including at least one sequence of machine executable instructions. A
10 medium bears the executable instructions in machine form and executes the instructions by one or more processors caused by the one or more processors. A sequence of video frames is extracted. Each of the video frames is upsampled. The upsampled video frames are interpolated. The interpolated video frames are aligned and a single image is created from the aligned video frames.

15 The foregoing and other objects of the present invention are achieved by a computer system, a processor and a memory coupled to the processor. The memory has stored sequences of instructions which when executed by the processor causes the processor to perform the following. A sequence of video frames is extracted. Each of the video frames is upsampled. The upsampled
20 video frames are interpolated. The interpolated video frames are aligned and a single image is created from the aligned video frames.

Still other objects and advantages of the present invention will become readily apparent to those skilled in the art from the following detailed description, wherein the preferred embodiments of the invention are shown and described,
25 simply by way of illustration of the best mode contemplated of carrying out the invention. As will be realized, the invention is capable of other and different embodiments, and its several details are capable of modifications in various obvious respects, all without departing from the invention. Accordingly, the

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drawings and description thereof are to be regarded as illustrative in nature, and not as restrictive.

Brief Description of the Drawings

5 The present invention is illustrated by way of example, and not by limitation, in the figures of the accompanying drawings, wherein elements having the same reference numeral designations represent like elements throughout and wherein:

10 Figure 1 is a high-level block diagram of a computer architecture usable with the present invention;

 Figures 2A and 2B are illustrations of a sequence of two consecutive video frames;

 Figures 3A and 3B are illustrations of a sequence of two consecutive edge detected frames corresponding to Figures 2A and 2B;

15 Figures 4A and 4B are illustrations of a sequence of consecutive frames with structures identified corresponding to Figures 3A and 3B;

 Figures 5A and 5B are illustrations of consecutive frames showing matched structures;

20 Figures 6A and 6B are flow diagrams according to the present invention of constructing a video mosaic;

 Figure 7 is a flow diagram of matching identified structures;

 Figure 8 is a flow diagram of edge detection;

 Figure 9 is a series of five resolution images;

25 Figure 10 is an upsampled sparsely populated matrix corresponding to the images of Figure 7;

 Figure 11 is an enlargement of adjacent pixels in a small section from Figure 10;

 Figure 12 are five interpolated images corresponding to Figure 10;

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Figure 13 is a final image after x, y alignment and filtering; and

Figure 14 is a flow diagram according to the present invention of enhancing a video mosaic.

5 Best Mode for Carrying Out the Invention

A method and apparatus for enhancing an image from a video mosaic taken are described. In the following description, for purposes of explanation, numerous specific details are set forth in order to provide a thorough understanding of the present invention. It will be apparent, however, that the
10 present invention may be practiced without these specific details. In other instances, well-known structures and devices are shown in block diagram form in order to avoid unnecessarily obscuring the present invention.

Hardware Overview

15 Figure 1 is a block diagram illustrating an exemplary computer system 100 upon which an embodiment of the invention may be implemented. The present invention is usable with currently available personal computers, mini-mainframes and the like. Advantageously, the present invention reduces the amount of processing capability required and can be processed on-board a UAV.

20 Computer system 100 includes a bus 102 or other communication mechanism for communicating information, and a processor 104 coupled with the bus 102 for processing information. Computer system 100 also includes a main memory 106, such as a random access memory (RAM) or other dynamic storage device, coupled to the bus 102 for storing information and instructions to be
25 executed by processor 104. Main memory 106 also may be used for storing temporary variables or other intermediate information during execution of instructions to be executed by processor 104. Computer system 100 further includes a read only memory (ROM) 108 or other static storage device coupled to

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the bus 102 for storing static information and instructions for the processor 104. A storage device 110, such as a magnetic disk or optical disk, is provided and coupled to the bus 102 for storing information and instructions.

Computer system 100 may be coupled via the bus 102 to a display 112,
5 such as a cathode ray tube (CRT) or a flat panel display, for displaying information to a computer user. An input device 114, including alphanumeric and other keys, is coupled to the bus 102 for communicating information and command selections to the processor 104. Another type of user input device is cursor control 116, such as a mouse, a trackball, or cursor direction keys for
10 communicating direction information and command selections to processor 104 and for controlling cursor movement on the display 112. This input device typically has two degrees of freedom in two axes, a first axis (e.g., x) and a second axis (e.g., y) allowing the device to specify positions in a plane.

The invention is related to the use of a computer system 100, such as the
15 illustrated system, to display an enhanced image of a video mosaic. According to one embodiment of the invention, the enhanced image of the video mosaic is provided by computer system 100 in response to processor 104 executing sequences of instructions contained in main memory 106. Such instructions may be read into main memory 106 from another computer-readable medium, such as
20 storage device 110. However, the computer-readable medium is not limited to devices such as storage device 110. For example, the computer-readable medium may include a floppy disk, a flexible disk, hard disk, magnetic tape, or any other magnetic medium, a CD-ROM, any other optical medium, punch cards, paper tape, any other physical medium with patterns of holes, a RAM, a PROM, an
25 EPROM, a FLASH-EPROM, any other memory chip or cartridge, a carrier wave embodied in an electrical, electromagnetic, infrared, or optical signal, or any other medium from which a computer can read. Execution of the sequences of instructions contained in the main memory 106 causes the processor 104 to perform the process steps described below. In alternative embodiments, hard-

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wired circuitry may be used in place of or in combination with computer software instructions to implement the invention. Thus, embodiments of the invention are not limited to any specific combination of hardware circuitry and software.

Computer system 100 also includes a communication interface 118
5 coupled to the bus 102. Communication interface 108 provides a two-way data communication as is known. For example, communication interface 118 may be an integrated services digital network (ISDN) card or a modem to provide a data communication connection to a corresponding type of telephone line. As another example, communication interface 118 may be a local area network (LAN) card
10 to provide a data communication connection to a compatible LAN. In the preferred embodiment communication interface 118 is coupled to a virtual blackboard. Wireless links may also be implemented. In any such implementation, communication interface 118 sends and receives electrical, electromagnetic or optical signals which carry digital data streams representing
15 various types of information. Of particular note, the communications through interface 118 may permit transmission or receipt of the enhanced image of the video mosaic. For example, two or more computer systems 100 may be networked together in a conventional manner with each using the communication interface 118.

20 Network link 120 typically provides data communication through one or more networks to other data devices. For example, network link 120 may provide a connection through local network 122 to a host computer 124 or to data equipment operated by an Internet Service Provider (ISP) 126. ISP 126 in turn provides data communication services through the world wide packet data
25 communication services through the world wide packet data communication network now commonly referred to as the "Internet" 128. Local network 122 and Internet 128 both use electrical, electromagnetic or optical signals which carry digital data streams. The signals through the various networks and the signals on network link 120 and through communication interface 118, which carry the

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digital data to and from computer system 100, are exemplary forms of carrier waves transporting the information.

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 5 Computer system 100 can send messages and receive data, including program code, through the network(s), network link 120 and communication interface 118. In the Internet example, a server 130 might transmit a requested code for an application program through Internet 128, ISP 126, local network 122 and communication interface 118. In accordance with the invention, one such downloaded application provides for information discovery and visualization as described herein.

10 The received code may be executed by processor 104 as it is received, and/or stored in storage device 110, or other non-volatile storage for later execution. In this manner, computer system 100 may obtain application code in the form of a carrier wave.

As depicted in Figures 2A and 2B there are a plurality of structures 205,
 15 210, 220, 225, 230, 240, 242, 244, 246 and 248. As depicted in photos 200 and 250, a building structure 205 is located at the lower left hand corner of both frames. As is evident from frames 200 and 250, building structure 205 is not in the same location in each of the consecutive video frames 200, 250 because of the motion of the camera. Structures 215, 220 and 225 are building structures which
 20 are in the upper right hand portion of video frames 200 and 250. Structure 230 is a building structure having multiple sides and having a v-shaped portion 232. A plurality of automobiles 240-248 are parked adjacent to building structure 230.

Referring now to Figures 3A and 3B, the various structures described in Figures 2A and 2B have been detected using an edge detecting process by
 25 detecting the change in intensity from one pixel to adjacent pixels. This will be described in greater detail below.

Figures 4A and 4B depict consecutive frames with structures having been identified. Figures 5A and 5B depict consecutive frames showing matched

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structures according to the present invention. Figures 2A-5B will now be explained with reference to the process of the present invention.

Sub A² Refer now to Figures 6A and 6B showing the process of the present invention. At step 605 the process is started. A step 610, individual frames are
 5 extracted from the library. As depicted in Figures 2A and 2B, frames 200 and 250 were extracted from the library. At step 615, the extracted individual frames are converted to a black and white format. At step 620, edge detection is performed by detecting change and intensity from one pixel to adjacent pixels. As depicted in Figures 3A and 3B, the outlines of various structures are detected.
 10 At step 625, lines are drawn at changes of intensity as depicted in Figure 3. At step 630, regions of interest are determined. At step 635, the regions of interest are correlated as explained with reference to Figures 7A and 7B. At step 640, image registration is performed by compensating for platform/camera movement. The registration process accounts for motion of the camera by determining the
 15 frame-to-frame x-y offsets, zoom and rotation. At step 645, frame overlay is performed. At step 650, the video mosaic can be viewed. At step 655 the process is ended.

Sub A³ Refer now to Figure 7 where at step 705 the process is started. At step 710, the centroid region of interest (ROI) is calculated. At step 715, the centroid is
 20 compared with centroids of next to adjacent frame. At step 720, centroids are selected which are within ariel tolerances. At step 725, there is a full correlation of average distance from every pixel and corresponding structure. At step 730, if the difference is consistent the structure is identified as a potential match. At step 735, steps 705-730 are repeated for other structures that fall within error
 25 tolerance. At step 740, the stored difference calculations are analyzed and select matches are based on pixels within structure having the most consistent differences. The analysis includes looking for frame-to-frame location as indicated by the difference calculation. This consistency will yield x-y translation, rotation and focal length changes.

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Sub A⁴ → Now referring to Figure 8, the process is started at step 805. At step 810, the frame is searched for an edge. At step 815, adjacent "on" pixels are followed until an "off" pixel is detected. At step 820, it is determined the locations of the on pixels and these locations are stored. At step 825, the number of on pixels is counted within the structure which must exceed a preset threshold. At step 830, the value of the pixels within a designated structure is changed to avoid use in future structures. At step 835, steps 805-830 are repeated until the entire images in structure detected. At step 840, the process is ended.

Sub A⁵ → As depicted in Figure 9, five video frames are extracted which were taken at 30 frames a second. Thus, there are video frames 910, 920, 930, 940 and 950 which are extracted from a data library. The data library can be onboard the UAV.

As depicted in Figure 10, each of the five images is upsampled by a factor of 4. Referring to Figure 11, there are four pixels, 1-1, 1-5, 5-1 and 5-5 which were previously adjacent to each other but have now been upsampled by a factor of 4. Thus, a 5 x 5 matrix has been created. For example, pixel 1-1 has an intensity of .80; pixel 1-5 has an intensity of .60; pixel 5-1 has an intensity of .80; and pixel 5-5 has an intensity of .90.

The images are then aligned as discussed above with respect to Figures 2-9. After the images have been aligned, then an average value from each of the five images in sequence is taken as depicted in Figure 12. In Figure 12, there are a series of five images 1210, 1220, 1230, 1240 and 1250 which correspond to the images 910, 920, 930, 940, 950. These five images are then combined and averaged into a single image as depicted in Figure 13.

Sub A⁶ → Referring now to Figure 14, a flow diagram summarizing the steps of the present invention is illustrated. At step 1405, the process is started. At step 1410, a low resolution image registration is performed for a sequence of images. At step 1415, each of the images upsampled. As depicted in Figures 10 and 11, the images are upsampled by factor 4. Other upsampling factors could be used, but

the factor of 4 appears to be optimal, yielding the most consistent results. Less than 4 could be used, but the idea is to create the highest resolution possible. Using a factor greater than 4 will result in diminishing returns, in that the amount of memory and processor capacity required will not necessarily product a sufficiently higher quality image. At step 1420, an x, y registration is performed for the upsampled images. At step 1425, the upsampled images are then aligned. Using a simple correlation technique to determine the x-y frame-to-frame offsets. At step 1430, these aligned, upsampled images are then combined into a high resolution output image by performing a pixel-by-pixel average across all 5 of the upsampled aligned images. At step 1435, the process is ended.

It will be readily seen by one of ordinary skill in the art that the present invention fulfills all of the objects set forth above. After reading the foregoing specification, one of ordinary skill will be able to affect various changes, substitutions of equivalents and various other aspects of the invention as broadly disclosed herein. It is therefore intended that the protection granted hereon be limited only by the definition contained in the appended claims and equivalents thereof.

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Interpolation

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